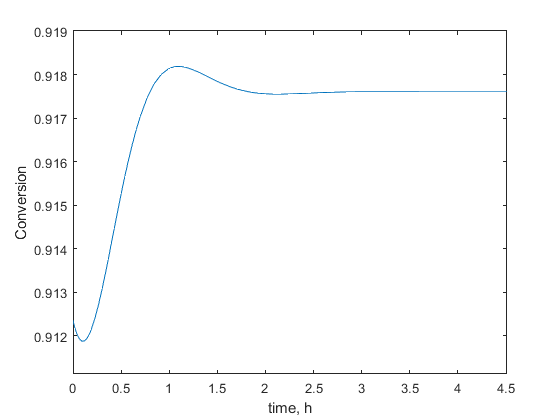
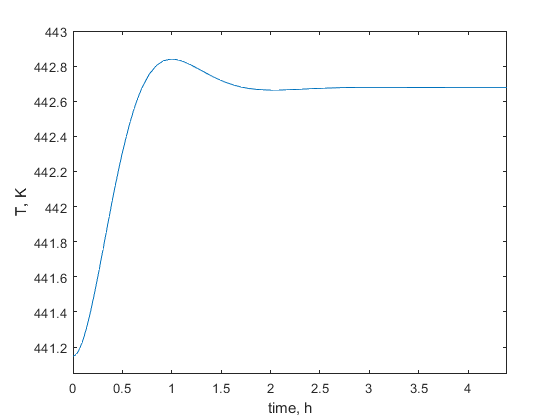
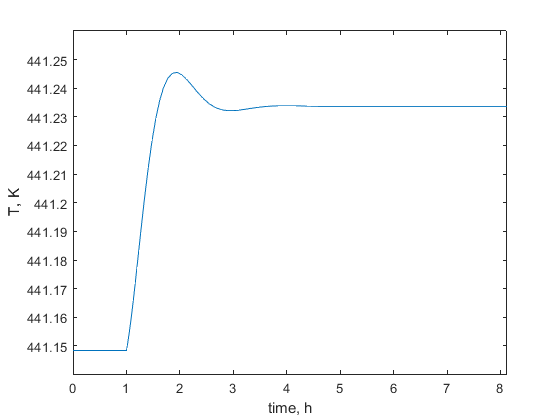
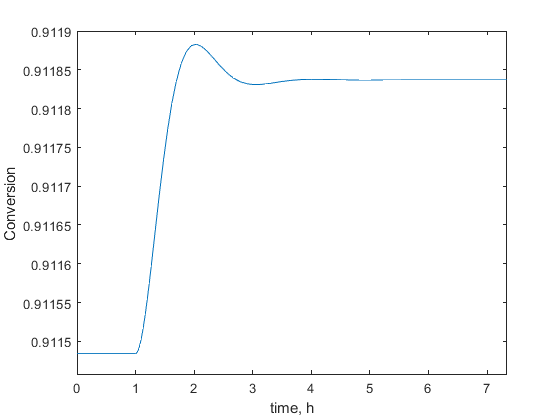
Step change in Ca0

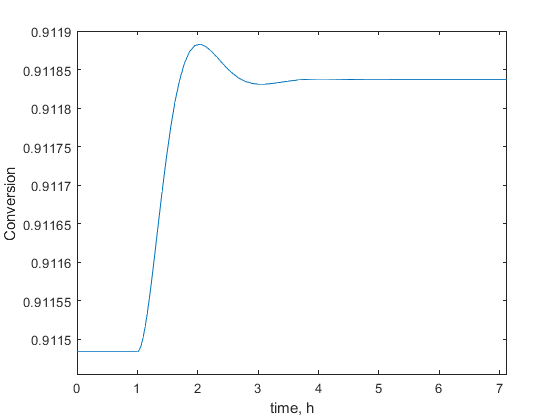
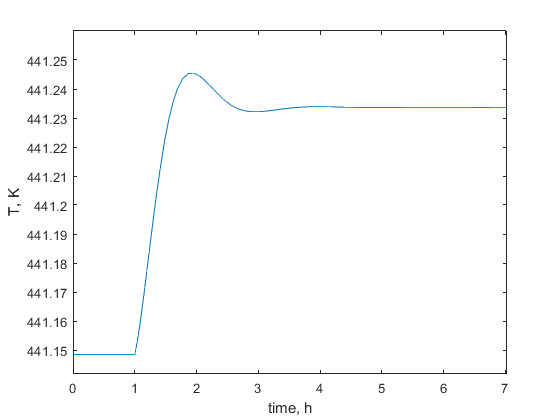


Step change Tf

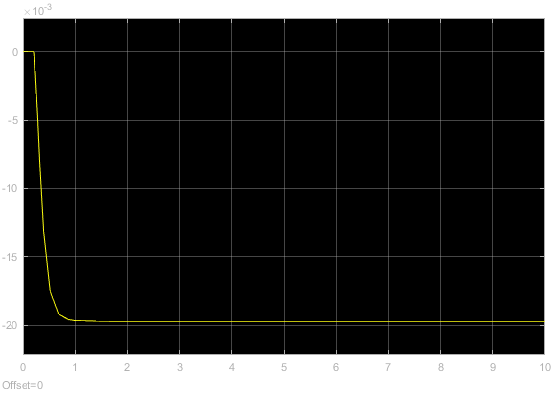




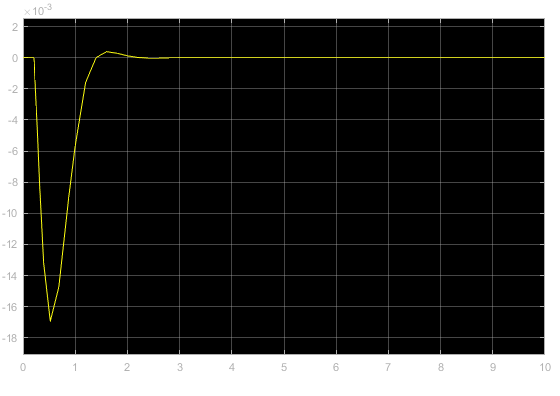
Step change Tc



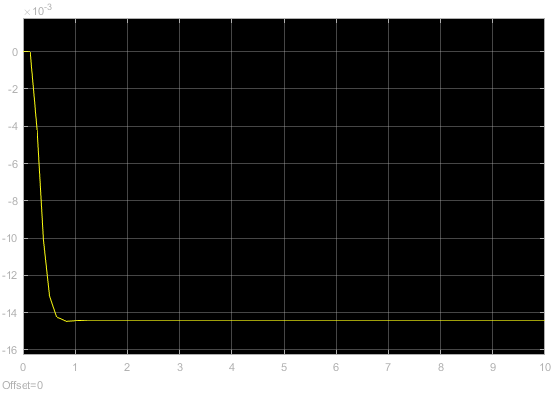
P controller conversion for given disturbances



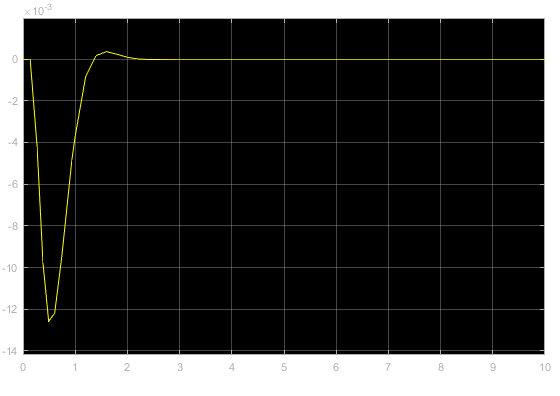
PI controller conversion for given disturbances



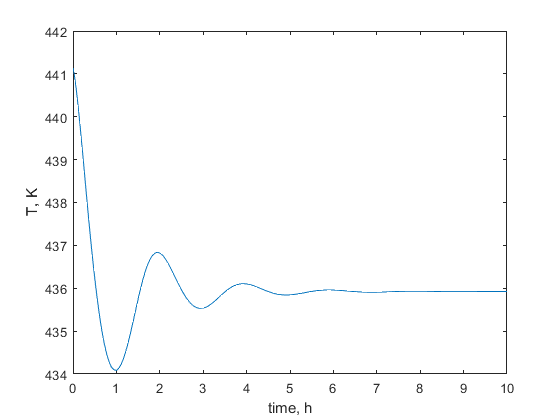
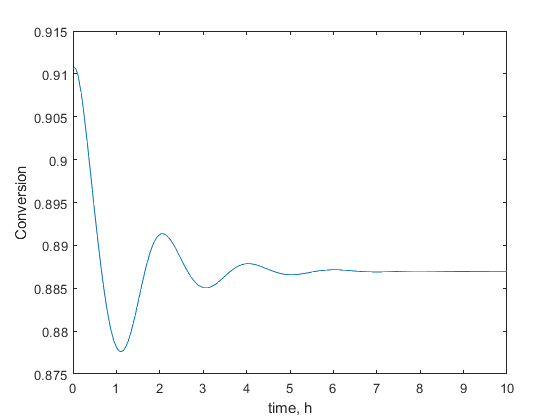
Offset in P controller for 5K decrease in Tf



Offset in PI controller for 5K decrease in Tf



P controller in real process



PI controller in real process

